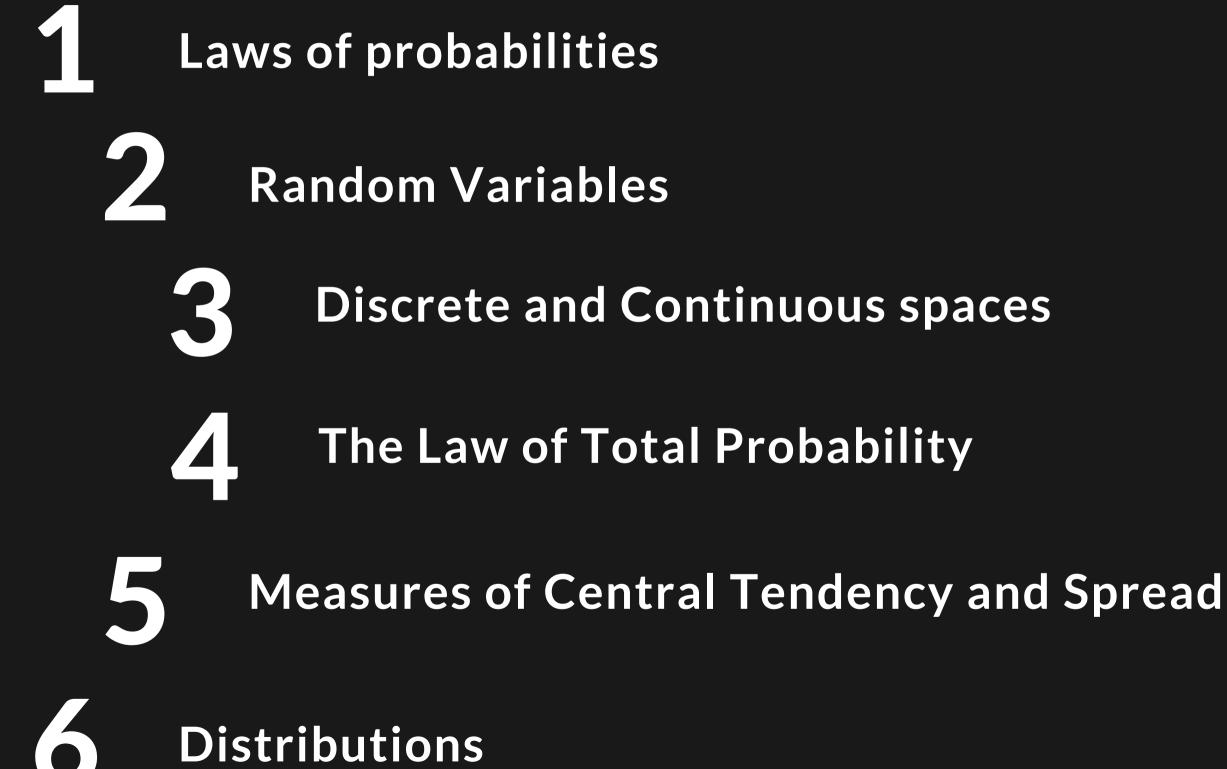
# Probability

PAL WORKSHOP



### **OUR GOAL FOR TODAY**





# 01 WHAT IS PROBABILITY?

- Concerns the study on uncertainty (loosely speaking).
- For certain types of events, we cannot predict the outcome with certainty in advance, e.g. tossing a coin or tossing a die.
- However we know the set of all possible outcomes for these events.
- We would like to use probability to measure the chance of something occurring in an experiment

### PROBABILITY

### H: What is it? C:DOG

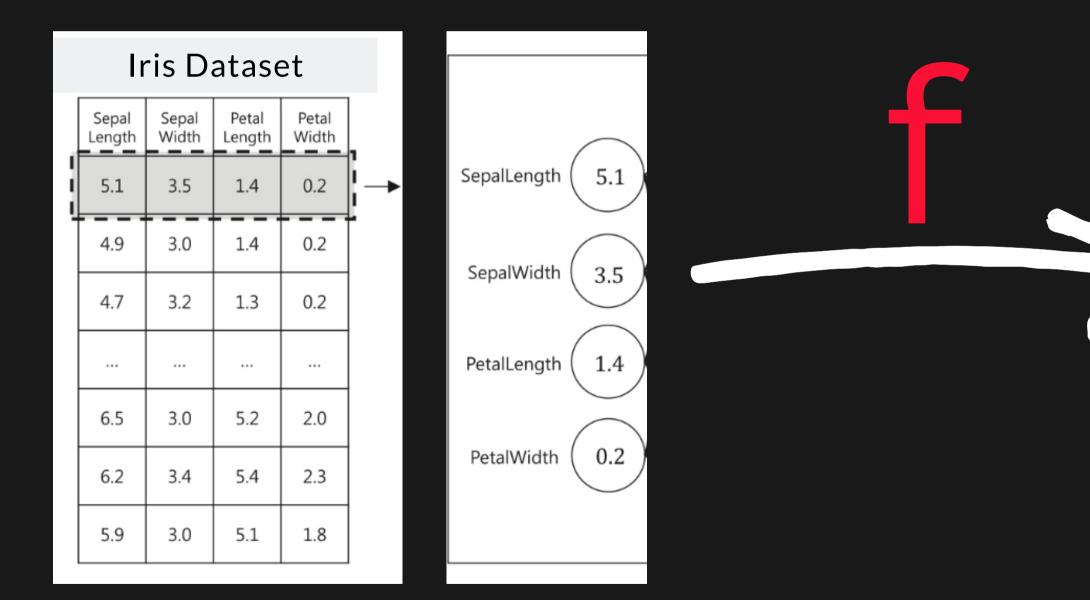


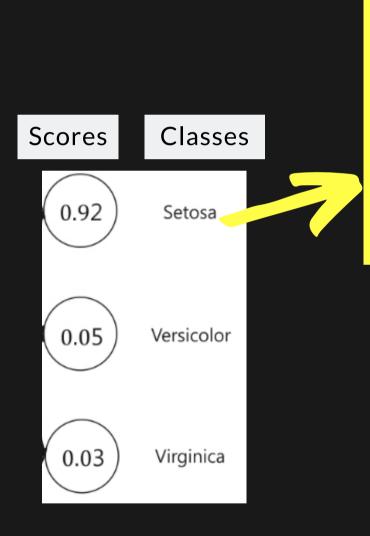


100%DOG true!

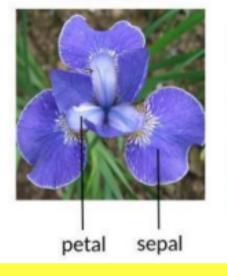
Then what is it?

### PROBABILITY





#### iris setosa

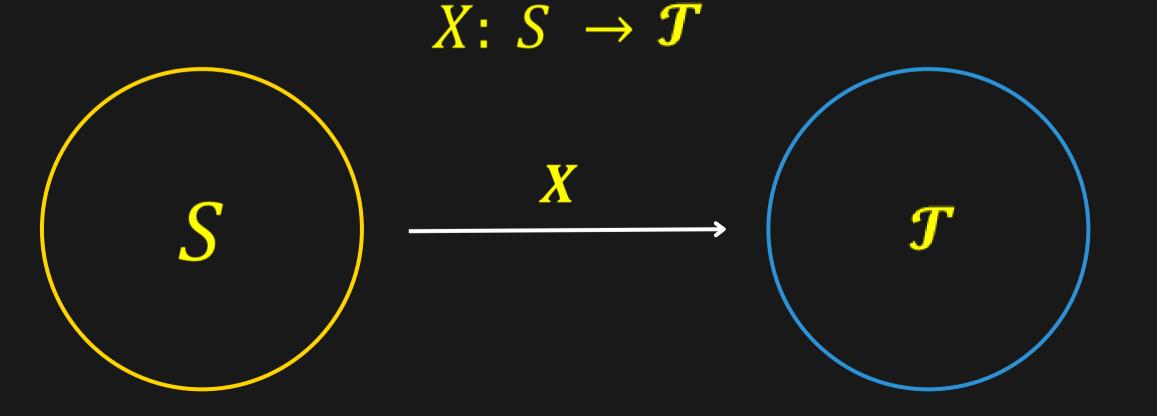




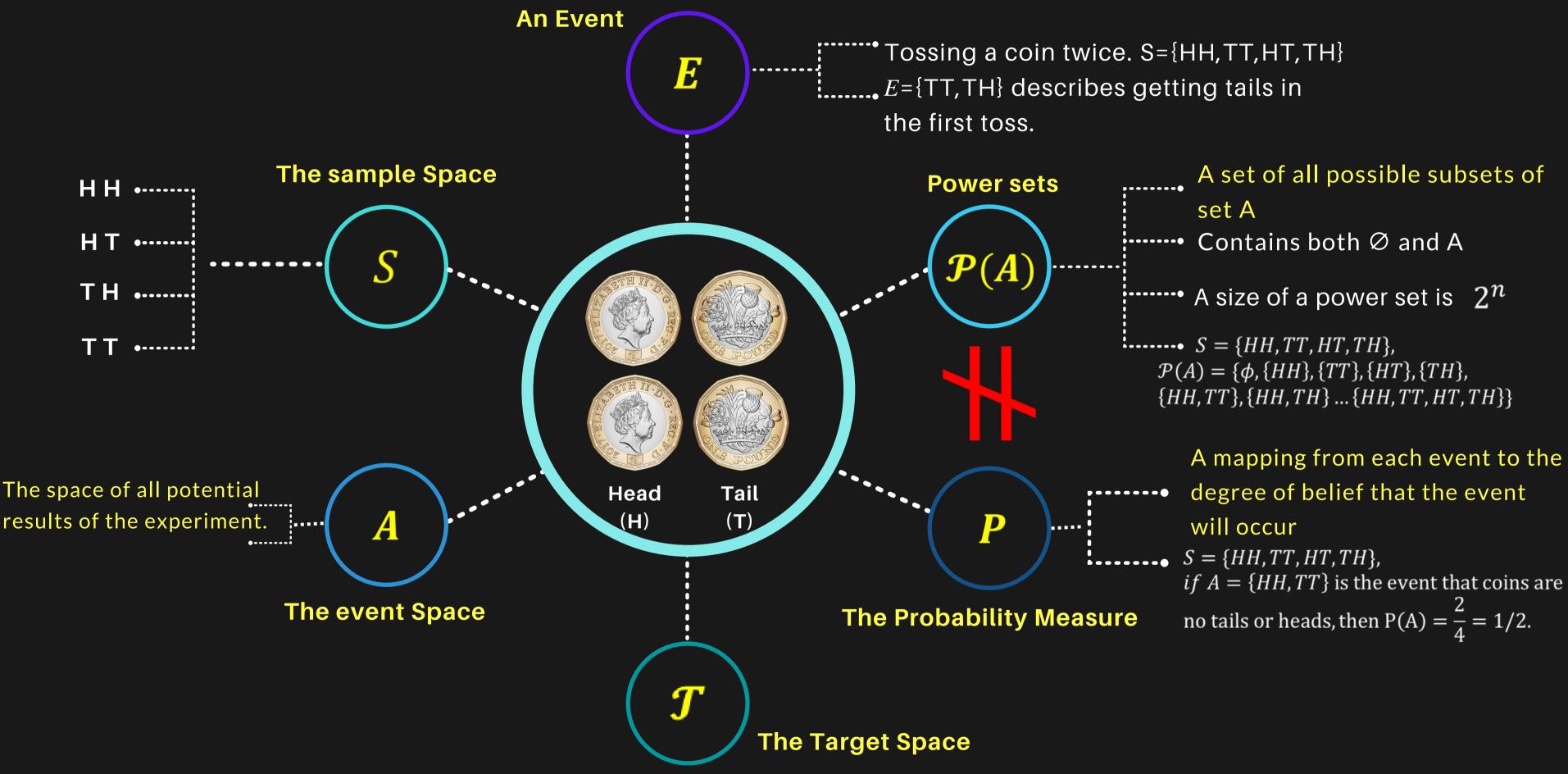


# 02 **RANDOM VARIABLES**

- The term itself is misleading as it is neither random nor is it a variable
- In fact it as a function

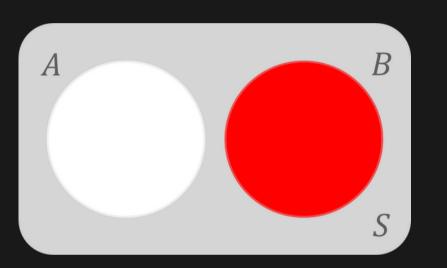


#### Let's consider the sample space of two successive coin tosses:

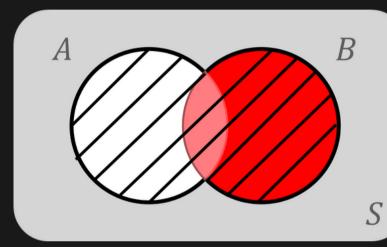


#### **PROBABILITIES AS SETS**

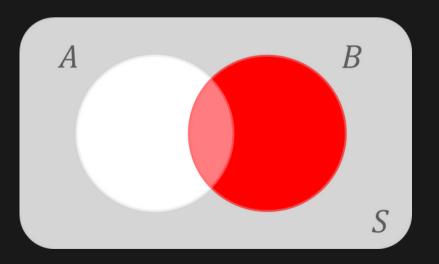
#### Mutually Exclusive events



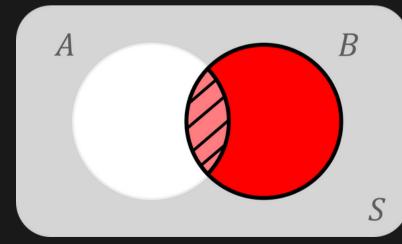
Probability of a union of two events  $P(A \cup B) = P(A) + P(B) - P(A \cap B)$ 



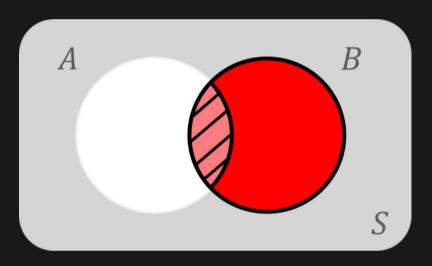
#### Non-mutually Exclusive events

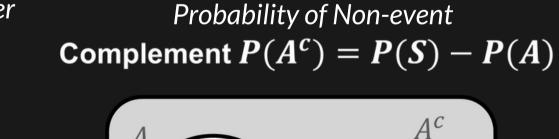


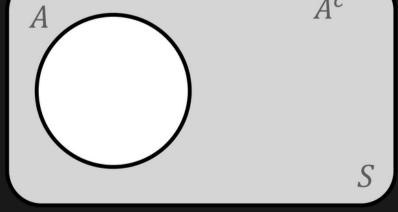
Conditional probability of one event given another  $P(A|B) = P(A \cap B)/P(B)$ 



#### Probability of a conjunction of two events $P(A \cap B) = P(A) \times P(B|A)$





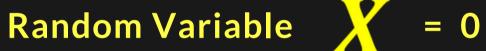




Random Variable X = 1 HEAD(H) X(H) = 1









X(T) = 0

## $\mathcal{T} = \{0, 1, 2\}$

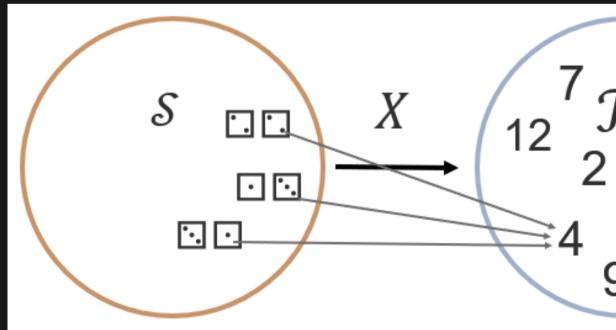
# $\mathbf{X}((H,H))=\mathbf{2}$ X((H,T)) = 1X((T,H)) = 1 $\mathbf{X}((T,T))=\mathbf{0}$

#### The Target Space $\mathcal{T}$

- Consider the set of all possible outcomes of throwing two six-sided dice.
- Then  $\Omega$  can be represented as:

 $\Box); (\Box, \Box); (\Box, \Box); (\Box, \Box); (\Box, \Box) \}$ 

- One possible random variable we can define is the sum of the tosses. •
- In that case  $\mathcal{T}$  will be a set of integers from 2 to 12.



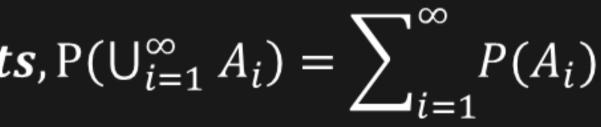
); 
$$(\Box, \Box)$$
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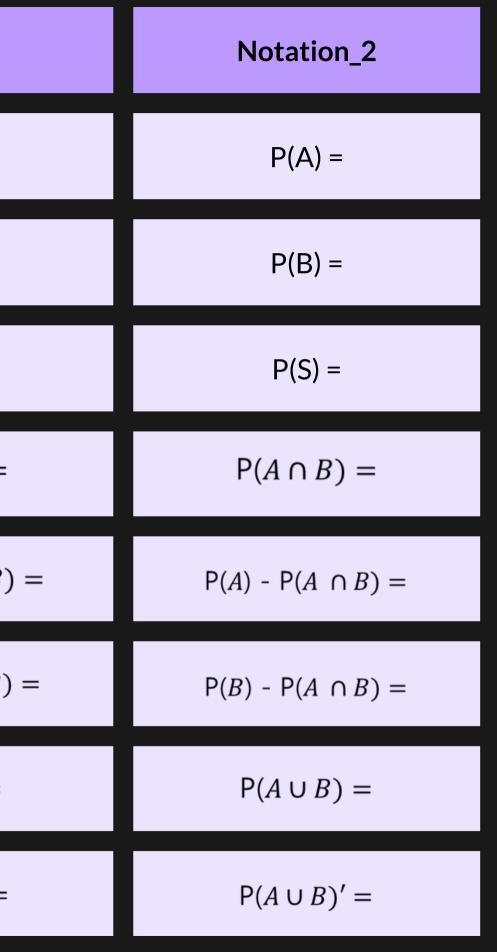
### PROBABILITY

## $(1) \ 0 \le P(A) \le 1$ (2) P(S) = 1(3) If $A_1, A_2, \dots$ are mutually exclusive events, $P(\bigcup_{i=1}^{\infty} A_i) = \sum_{i=1}^{\infty} P(A_i)$





In Words	Notation_1
All Heads	n(A) =
All Tails	n(B) =
All coins	n(S) =
Intersection: Both head and head	$n(A \cap B) =$
Only Heads: Head coins that are not tail coins	$n(A) - n(A \cap B)$
Only Tails: Tail coins that are not head coins	$n(B) - n(A \cap B)$
Union: Head or Tail	$n(A \cup B) =$
Everything else	$n(A \cup B)' =$



# **LET'S PRACTICE**



#### Q1. Probability of getting an even number on rolling a dice once. what are smple space(S), Event(E) and probability?

Q2. If A & B are two mutually exclusive events then  $P(A \cap B) = 0$  and  $P(A \cup B) = P(A) + P(B)$ .

 $A = \{Numbers greater than or equal to 4 in a dice roll\} = \{4,5,6\}$  $B = \{Numbers lesser than or equal to 4 in a dice roll\} = \{1,2,3,4\}$  $Then, what is P(A \cup B)?$ 

# $= 0 \text{ and } P(A \cup B) = P(A) + P(B).$ $\{4,5,6\}$ $\{2,3,4\}$

# DISCRETE & CONTINUOUS PROBABILITIES

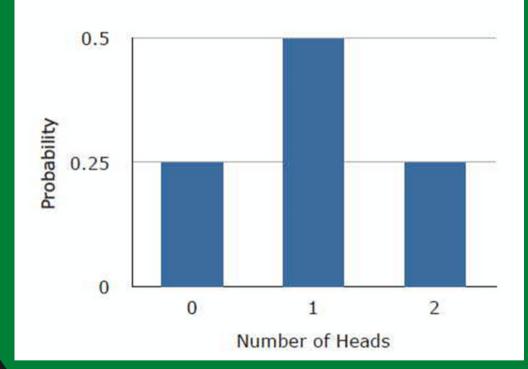
- It is important to understand the difference between target space types.
- Discrete random variables:
  - Variable can take on a *discrete* set of values.
  - Value can be obtained by counting.
- Continuous random variables:
  - Variable can take on a continuous set of values.
  - Value can be obtained by measuring.



## **DISCRETE PROBABILITY**

- The probability that a random variable X takes a particular value is  $x \in T$  denoted as P(X = x)
- This expression is also called *probability* mass function.

P(X = 0) = 0.25P(X = 1) = 0.5P(X = 2) = 0.25



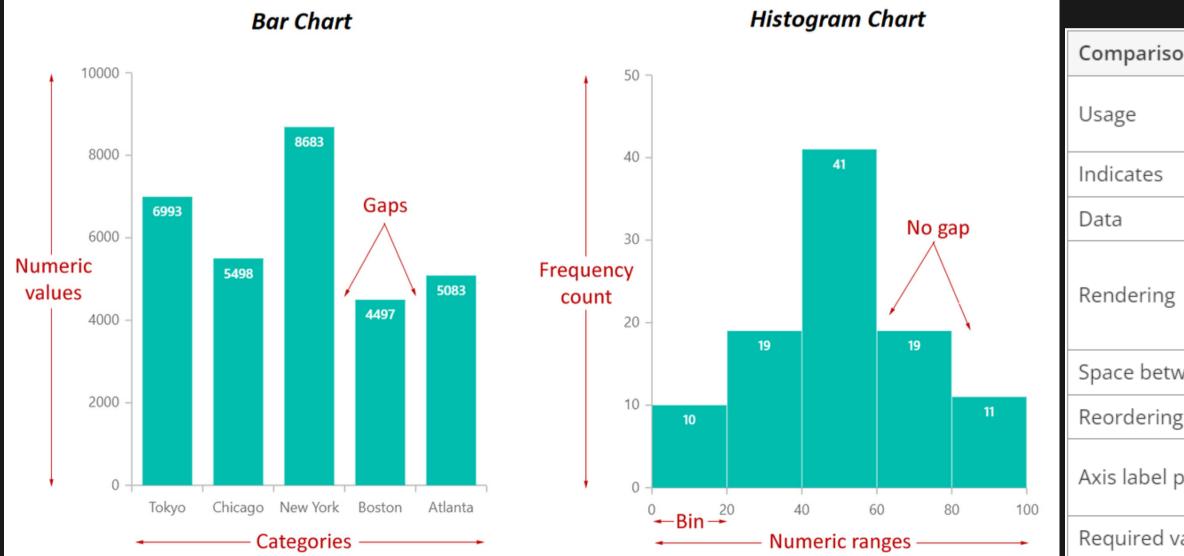
### **DISCRETE PROBABILITY**

• When the target space is discrete we can imagine the probability distribution of multiple random variables as a multidimensional array of numbers

<i>y</i> <sub>3</sub>	0.1	0.07	0.06	0.03	0.1	► Joint pr = $P(X)$
<i>y</i> <sub>2</sub>	0.12	0.09	0.02	0.01	0.05	Margina that X ta
<i>y</i> <sub>1</sub>	0.18	0.01	0.11	0.02	0.03	<ul> <li>Condition</li> <li>the value</li> </ul>
	<i>x</i> <sub>1</sub>	<i>x</i> <sub>2</sub>	<i>x</i> <sub>3</sub>	$x_4$	<i>x</i> <sub>5</sub>	

- robability is defined as p(x, y) $= x_i, Y = y_i$
- al probability p(x) represents the probability akes the value  $x_i$  irrespective to the value of Y.
- onal probability p(y|x) will only consider Le of Y for a particular value of X.

## What's difference between bar graph and histogram?



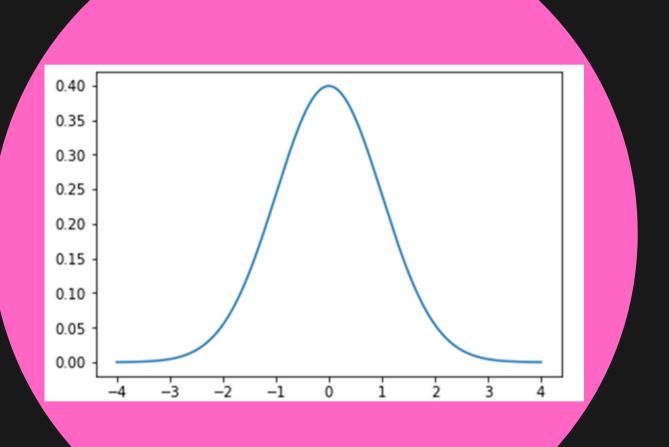
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on terms	Bar chart	Histogram chart
	To compare different categories of data.	To display the frequency of occurrences.
	Discrete values.	Non-discrete values.
	Categorical data.	Quantitative data.
7	Each data point is rendered as a separate bar.	The data points are grouped and rendered based on the bin value.
ween bars	Can have space.	No space.
g bars	Can be reordered.	Cannot reordered.
placement	Axis labels can be placed on or between the ticks.	Axis labels are placed on the ticks.
values	x and y.	Only y.

Reference: https://www.syncfusion.com/blogs/post/difference-between-bar-graph-and-histogram-chart.aspx

### **CONTINUOUS PROBABILITY**

- Target spaces are intervals of the real line
- A *probability density function* is a function whose value at any given point in the sample space can be interpreted as providing a *relative likelihood* that the value of the random variable would be close to that sample.



# THE LAW OF TOTAL PROBABILITY

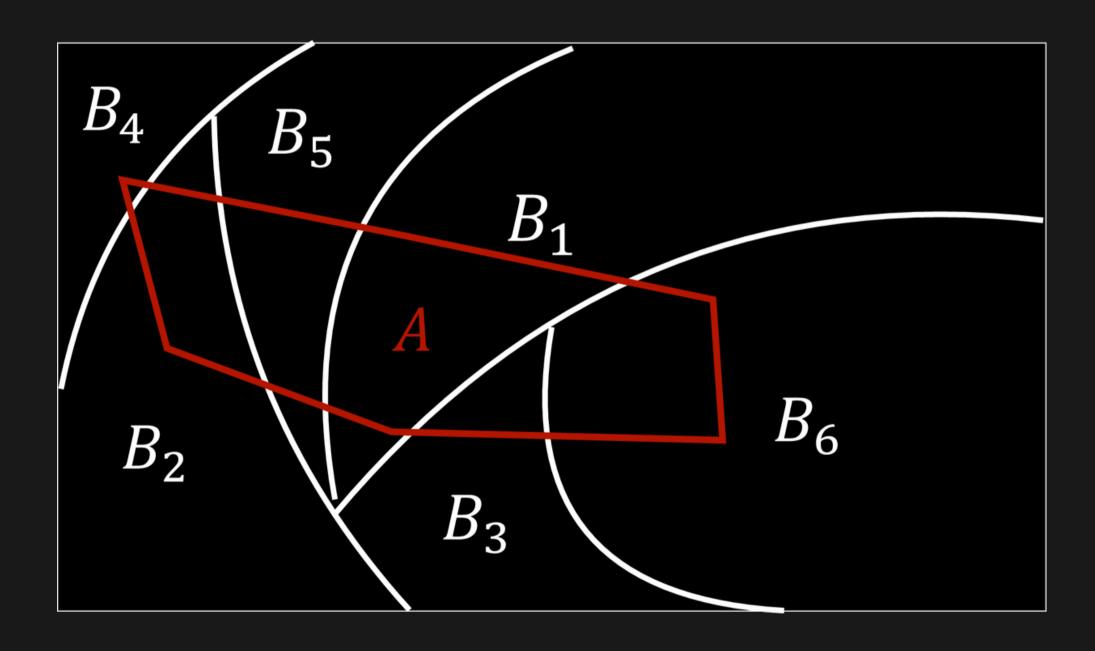
 Suppose B<sub>1</sub>,..., B<sub>n</sub> are mutually exclusive and collectively exhaustive events in a sample space. We can then sum/integrate over the set of states of variable B to get a marginal distribution of variable A.

$$P(A) = \sum_{i}^{n} P(A|B_i) P(B_i) P(B_i) = \sum_{i}^{n} P(A|B_i) P(B_i) P(B_i) = \sum_{i}^{n} P(A|B_i) P(B_i) P($$

## $P(A \cap B_i)$

### THE LAW OF TOTAL PROBABILITY

- Mutually exclusive no overlap.
- Collectively exhaustive cover the whole space.



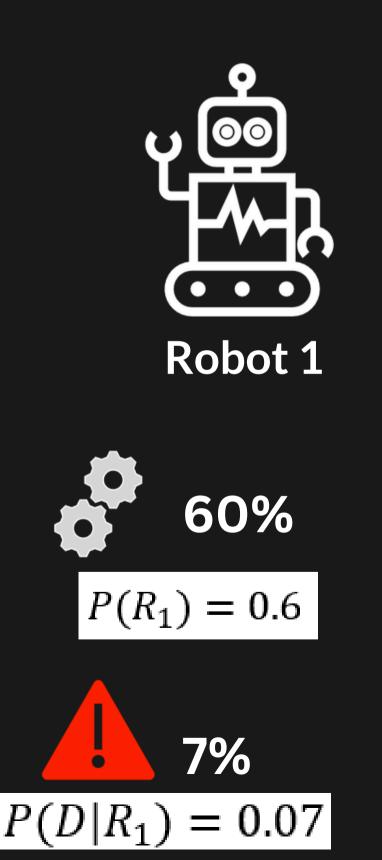
# **LET'S PRACTICE**

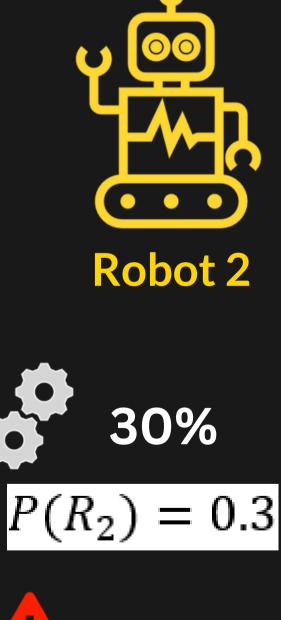


### Three robots are making parts at the Sussex factory. We know that:

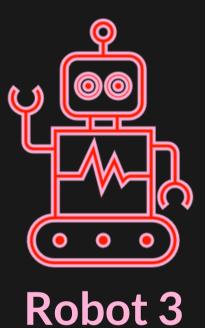
A rate of Making parts

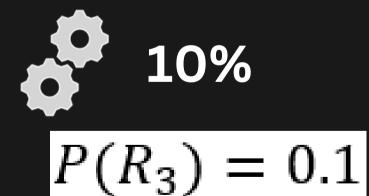


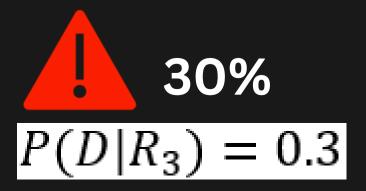




15% $P(D|R_2) = 0.15$  A rate of Deficiency of the parts, which the robot makes





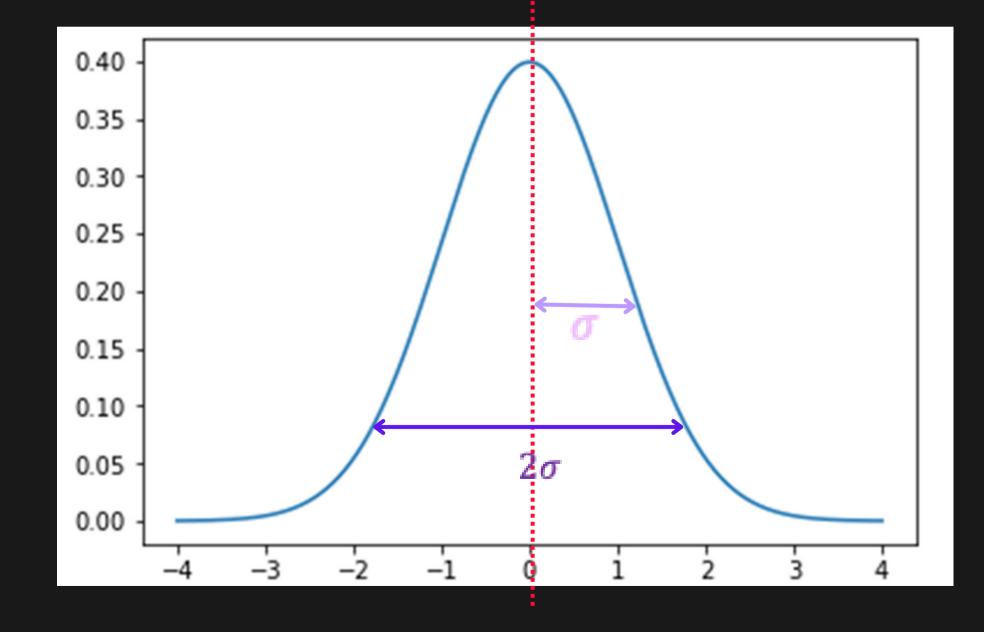


### What is the probability of a randomly selected part being defective?

# **P(D) = ?**

#### 05

# MEASURES OF CENTRAL TENDENCY AND SPREAD



# **EXPECTATION AND VARIANCE**

• Expected Value/Mean gives the weighted average of all possible outcomes of the random variable. Is not an expected outcome, but a theoretical mean!

• Variance represents the dispersion, i.e. how far a set of numbers is spread from the mean.

$$Var(X) = \mathbb{E}[(X - \mu)^2] = \sum_{x} (x - \mu)^2$$

• Standard Deviation is simply a square root of the variance

$$\sigma_X = \sqrt{Var(X)}$$

 $\mathbb{E}(X) = \sum x p(x)$ 



$$(-\mu)^2 p(x)$$

Definition

### Covariance



### Correlation

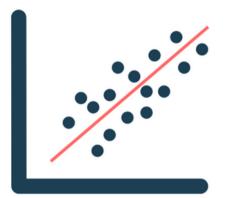
Corr[X,Y] = -

**Covariance** of two univariate random variables  $X,Y \in \mathbb{R}$  is given by the expected product of their deviations from their respected means.

$$Cov(X,Y) = \mathbb{E}_{X,Y}[(x - \mathbb{E}_X[x])][(y - \mathbb{E}_Y[y])]$$

- **Correlation** is the normalized form of Covariance.
- Is useful when we want to compare the covariances between different pairs of random variables.

$$\frac{Cov(X,Y)}{\sqrt{Var(X)Var(Y)}} \in [-1,1]$$



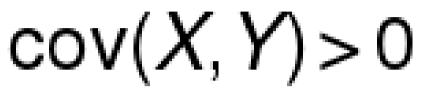
#### Positive correlation As one variable increases

so does the other variable.

Negative correlation As one variable increases the other variable decreases.

### No correlation

There is no relationship between the two variables.



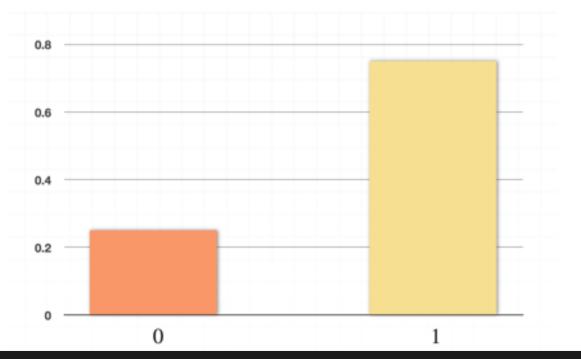
## cov(X, Y) < 0

## $cov(X, Y) \approx 0$

Reference: https://www.internetgeography.net/scatter-graphs-in-geography/

# 06 DISTRIBUTIONS **Bernoulli distribution**

- Models the set of possible outcomes for a single experiment.
- $X \in \{0,1\}$
- Parameter  $\rho \in [0,1]$  reflects the probability of getting a 1.
- PMF:  $f(x; p) = \rho^{x} (1 \rho)^{1-x}$
- $\mathbb{E}[X] = p$
- Example: tossing a biased coin.



# 06 DISTRIBUTIONS **Binomial distribution**

- A generalization of Bernoulli for  $\mathbb{N}$  random variables, i.e.  $X \in \mathbb{N}$ .
- Parameters  $\rho \in [0,1], n \in \mathbb{N} = 0,1,2,3,...$
- PMF:  $f(x; p, n) = {n \choose k} \rho^{x} (1 \rho)^{n-x}$
- $\mathbb{E}|X| = n\rho$

# 06 DISTRIBUTIONS Binomial distribution

Let's have a closer look at the PMF:

$$f(x; p, n) = \binom{n}{k} \rho^x (1 - \rho)^{n-x}$$

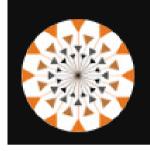
Combination

$$\binom{n}{k} = \frac{n!}{n!(n-k)!}$$

Where n is the total number of possible outcomes,

k is number of items you want to rearrange.

### 🕨 YouTube



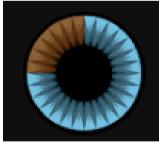
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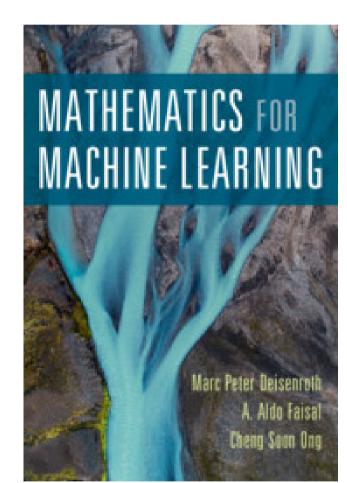
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# Sol

#### StatQuest with Josh Starmer 🔹

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### Textbook



# Useful materials