

# *P*(PAL) Workshop

05/12/2022 17:00 Future Technologies Lab

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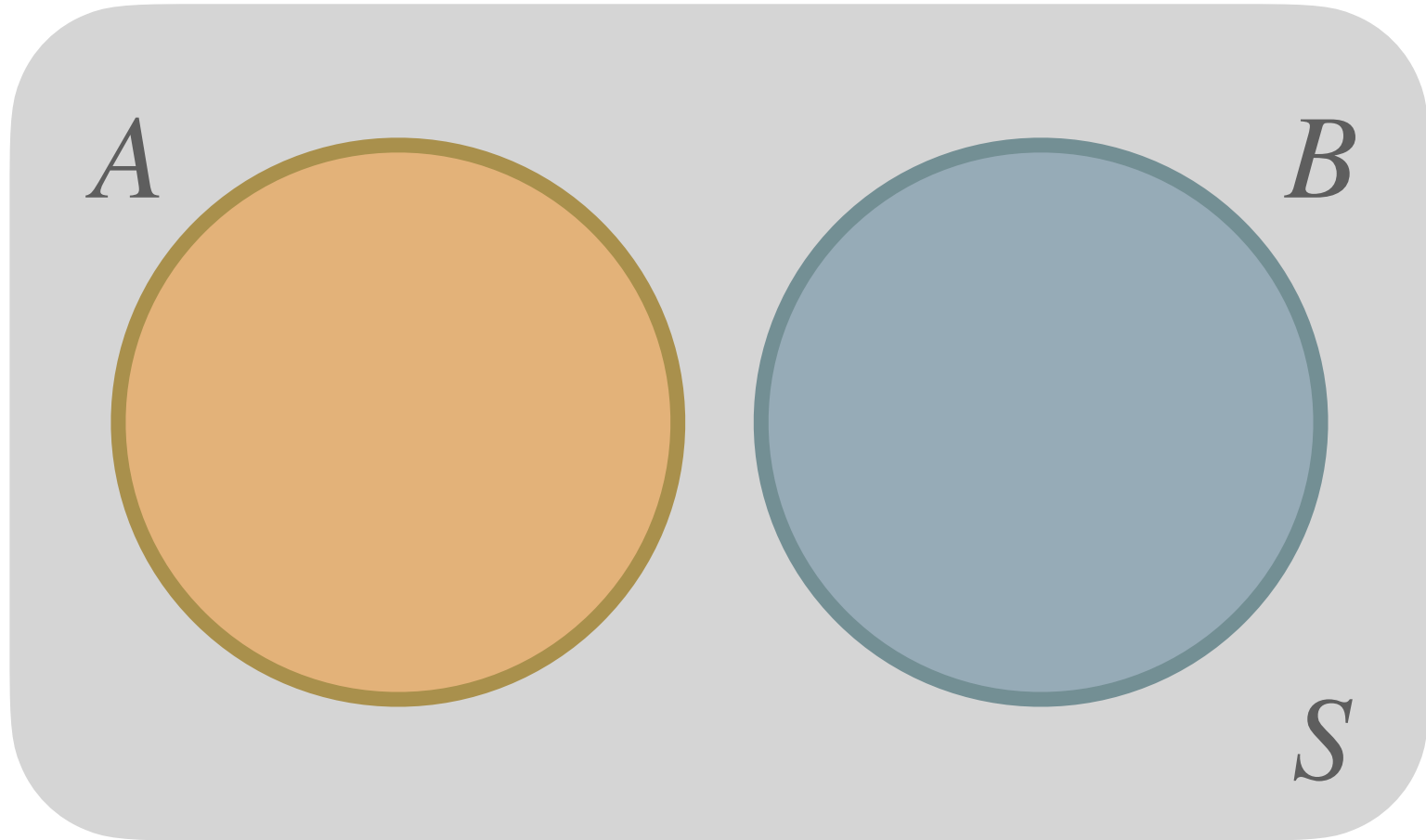
- Laws of probabilities
- Random Variables
- Discrete and Continuous spaces
- The Law of Total Probability
- Measures of Central Tendency and Spread
- Distributions

# What is Probability?

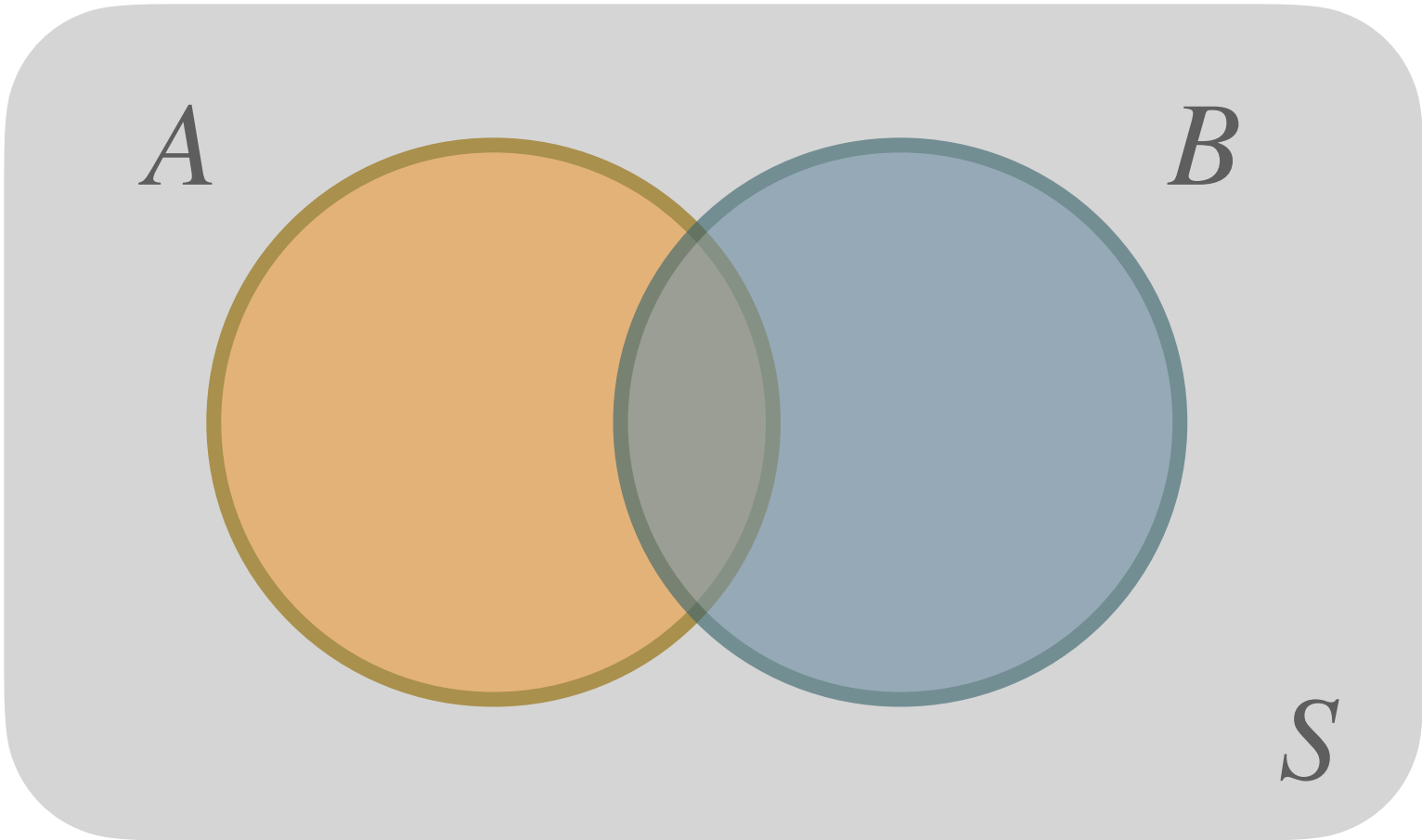
- Concerns the study on uncertainty (loosely speaking).
- For certain types of events, we cannot predict the outcome with certainty in advance, *e.g. tossing a coin or tossing a die.*
- However we know the set of all possible outcomes for these events.
- We would like to use probability to measure the chance of something occurring in an experiment.

# Probabilities as Sets

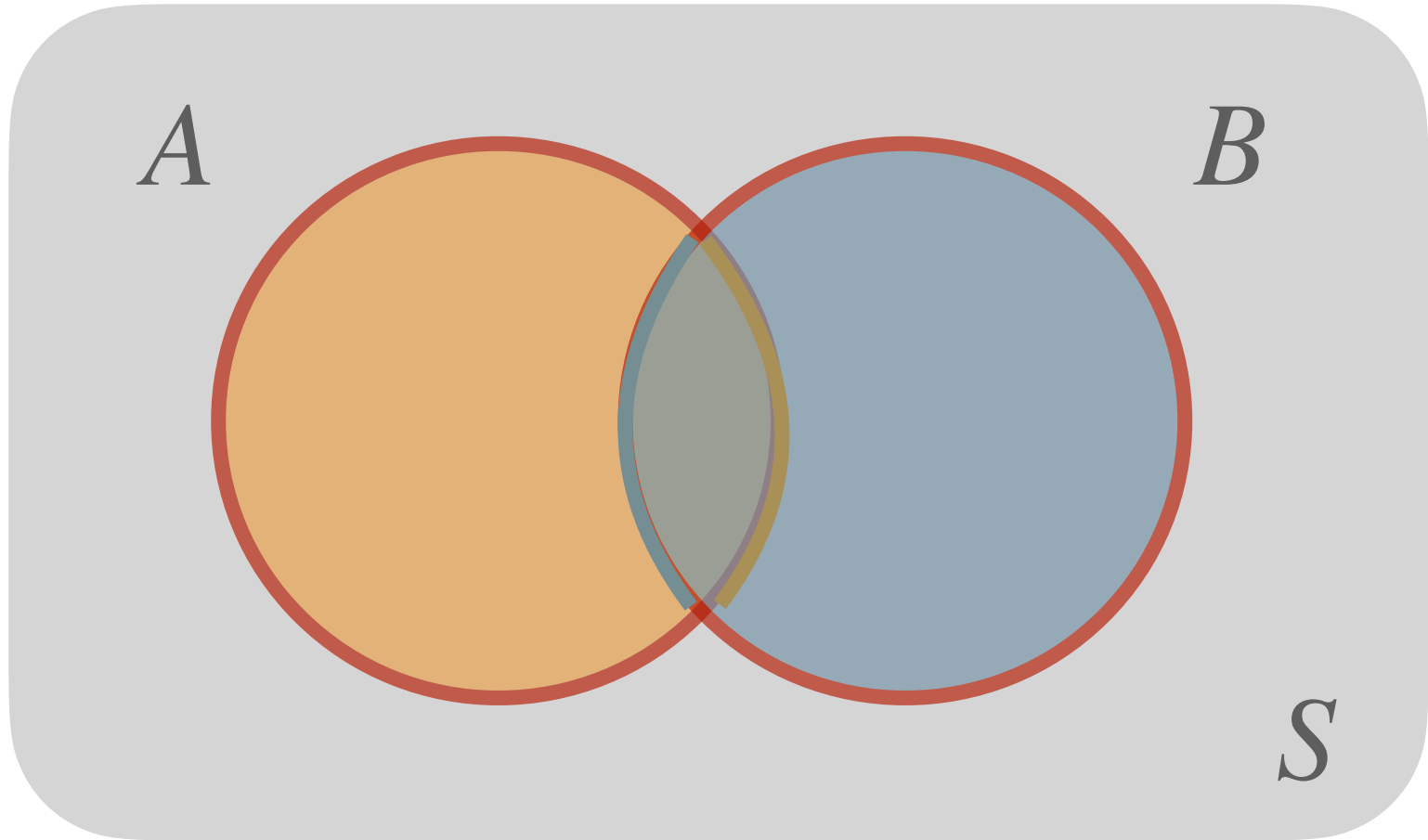
Mutually Exclusive events



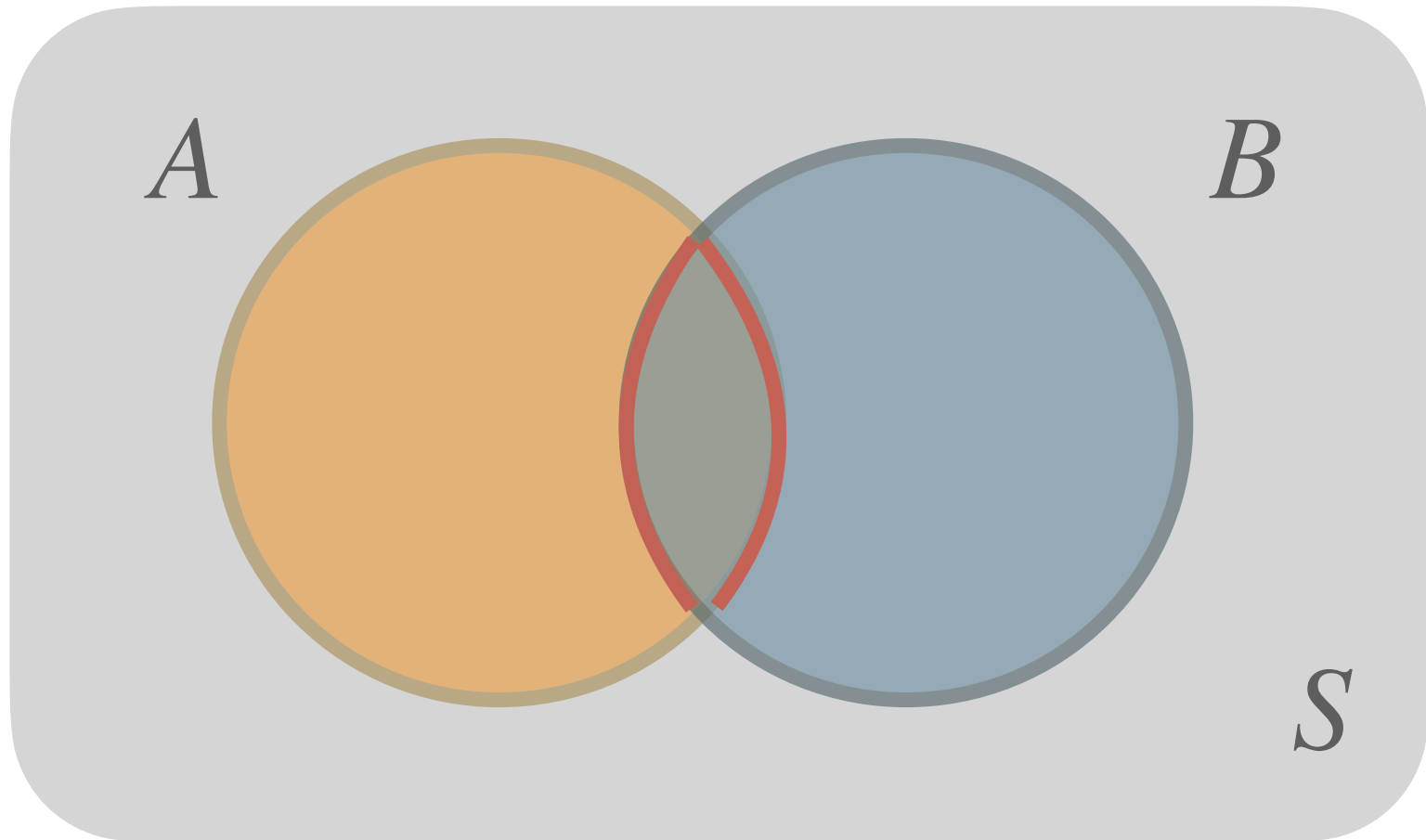
Non-mutually Exclusive events



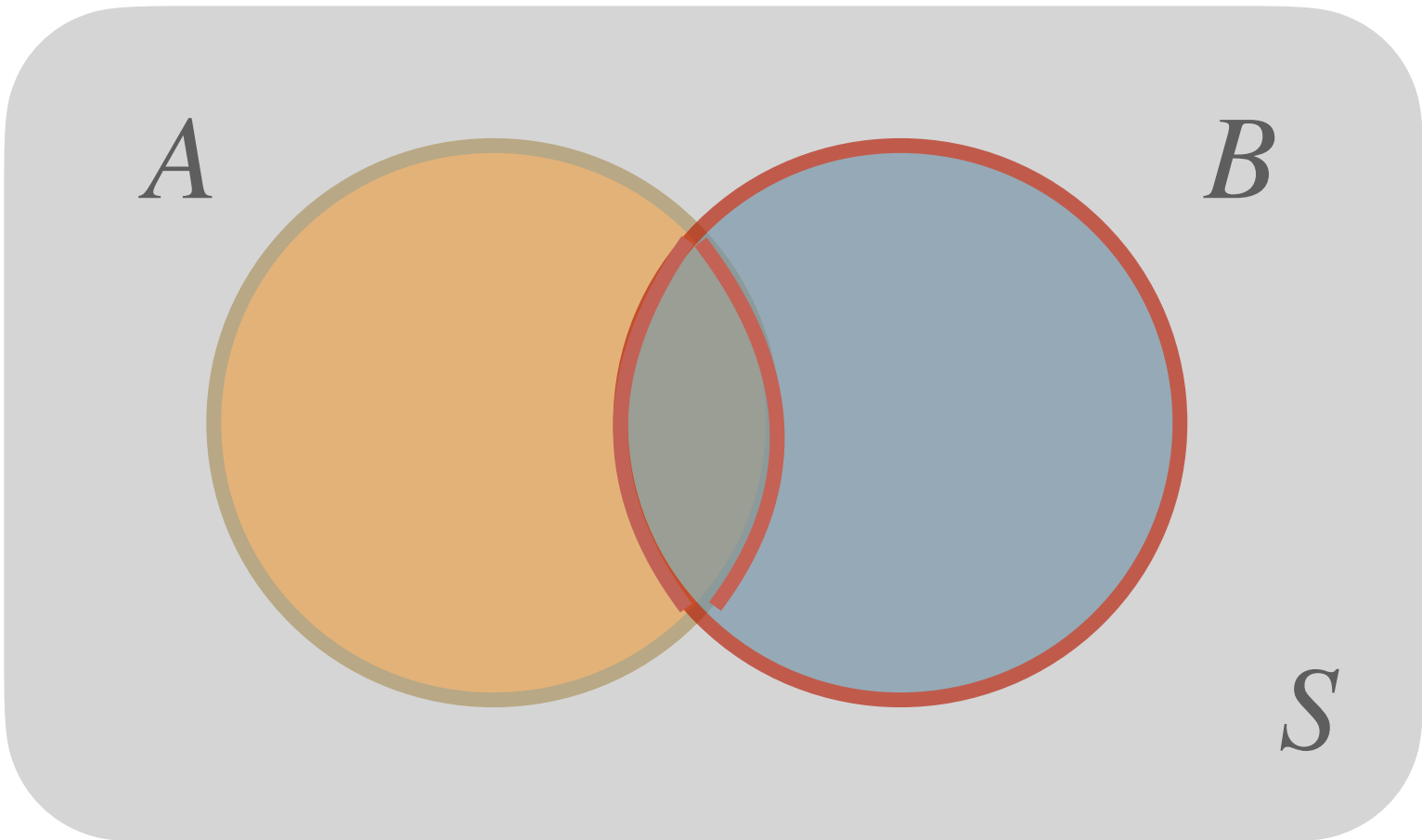
$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$



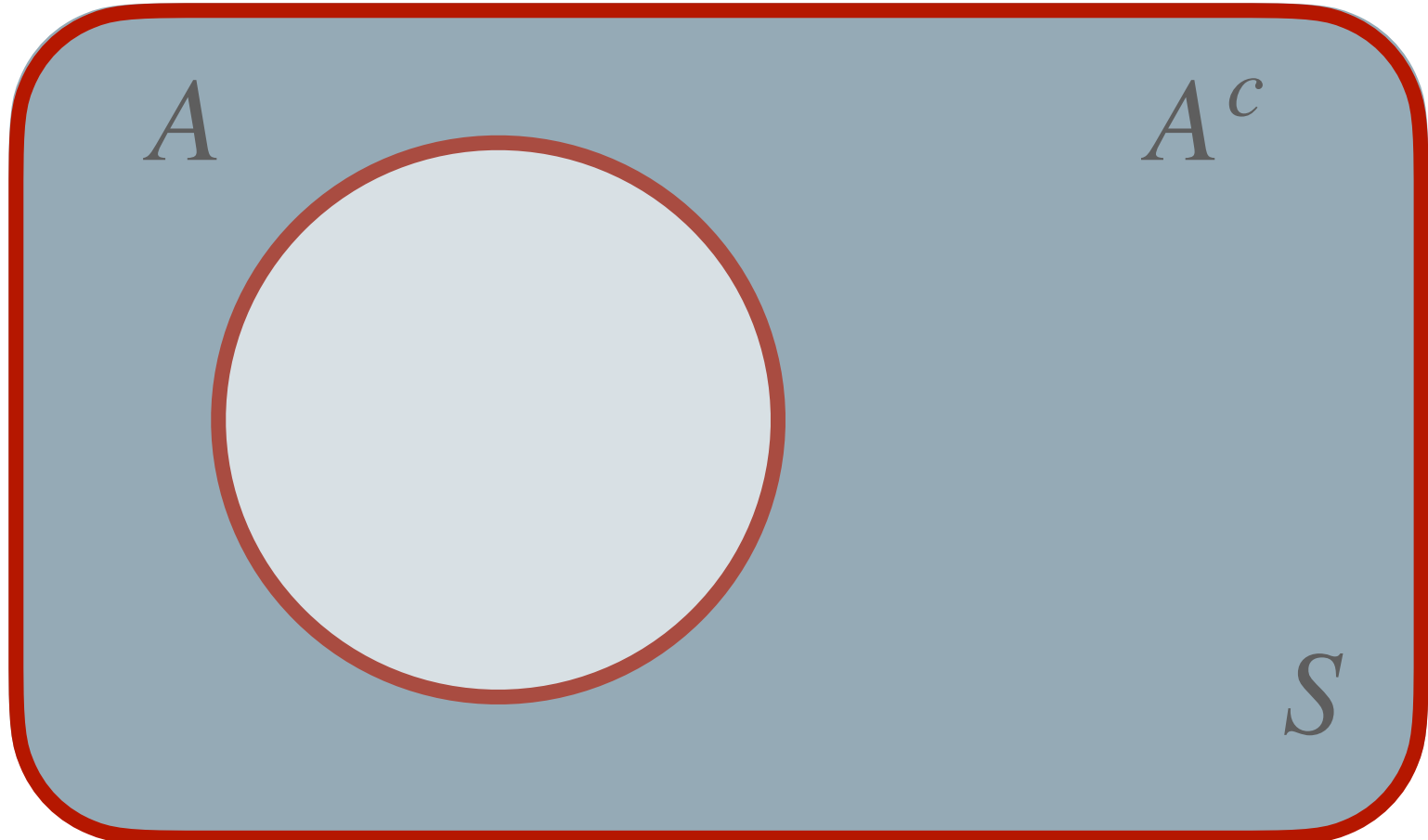
$$P(A \cap B) = P(A) \times P(B | A)$$



$$P(A | B) = P(A \cap B) / P(B)$$



Complement  $P(A^c) = P(S) - P(A)$



# Random Variables

## The Sample Space $\Omega$

- The set of all possible outcomes of the experiment.
- Let's consider the sample space of two successive coin tosses:

$$\Omega = \{hh, tt, ht, th\}$$

- A subset of the sample space  $\Omega$  is called an event  $E$ .
- Examples:
  1. Tossing a die.  $\Omega = \{1,2,3,4,5,6\}$ ,  $E = \{4\}$  describes *tossing a four*.
  2. Tossing a die.  $\Omega = \{1,2,3,4,5,6\}$ ,  $E = \{2,4,6\}$  describes *tossing an even number*.
  3. Tossing a coin twice.  $\Omega = \{hh, tt, ht, th\}$ ,  $E = \{tt, th\}$  describes *getting tails in the first toss*.

# Random Variables

## Power Sets

- Power set - a set of all possible subsets of set  $A$ .
- Denoted as  $\mathcal{P}(A)$ . *Do not confuse with probability!*
- Contains both  $\emptyset$  and  $A$ .
- A size of a power set is  $2^n$ , where  $n$  is the cardinality of set  $|\mathcal{P}(A)|$ .

# Random Variables

## Power Sets

- Example:
  - Set  $A = \{1,2,3\}$
  - Subsets of set  $A = \{\}, \{1\}, \{2\}, \{3\}, \{1,2\}, \{2,3\}, \{1,3\}, \{1,2,3\}$
  - $\mathcal{P}(A) = \{\{\}, \{1\}, \{2\}, \{3\}, \{1,2\}, \{2,3\}, \{1,3\}, \{1,2,3\}\}$

# Random Variables

## The Event Space $\mathcal{A}$

- The space of all potential *results* of the experiment.
- Describes *all* possible sets of events that can happen.
- For discrete probability distributions,  $\mathcal{A}$  is often the power set of  $\Omega$ .



# Random Variables

## The Probability Measure $P$

- A mapping from each event to the degree of belief that the event will occur.
- The probability of a single event lies in the interval  $[0,1]$ .
- $P(\Omega) = 1$

# Random Variables

## The Target Space $\mathcal{T}$

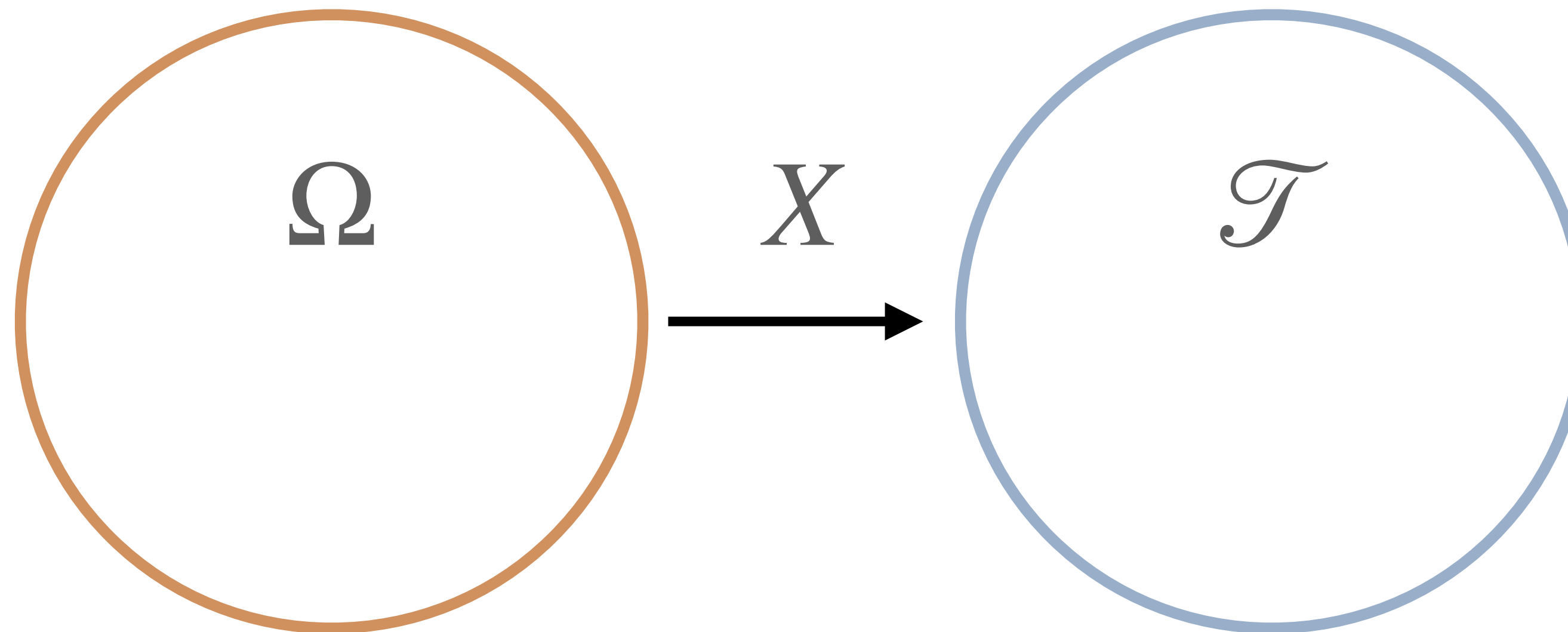
- A mapping from the sample space to the particular quantities of interest.
- Sounds a bit complicated but in fact this is a very simple idea!

# Random Variables

## Definition

- The term itself is misleading as it is neither random nor is it a variable.
- In fact it is a function!

$$X : \Omega \rightarrow \mathcal{T}$$



# Random Variables

## Example

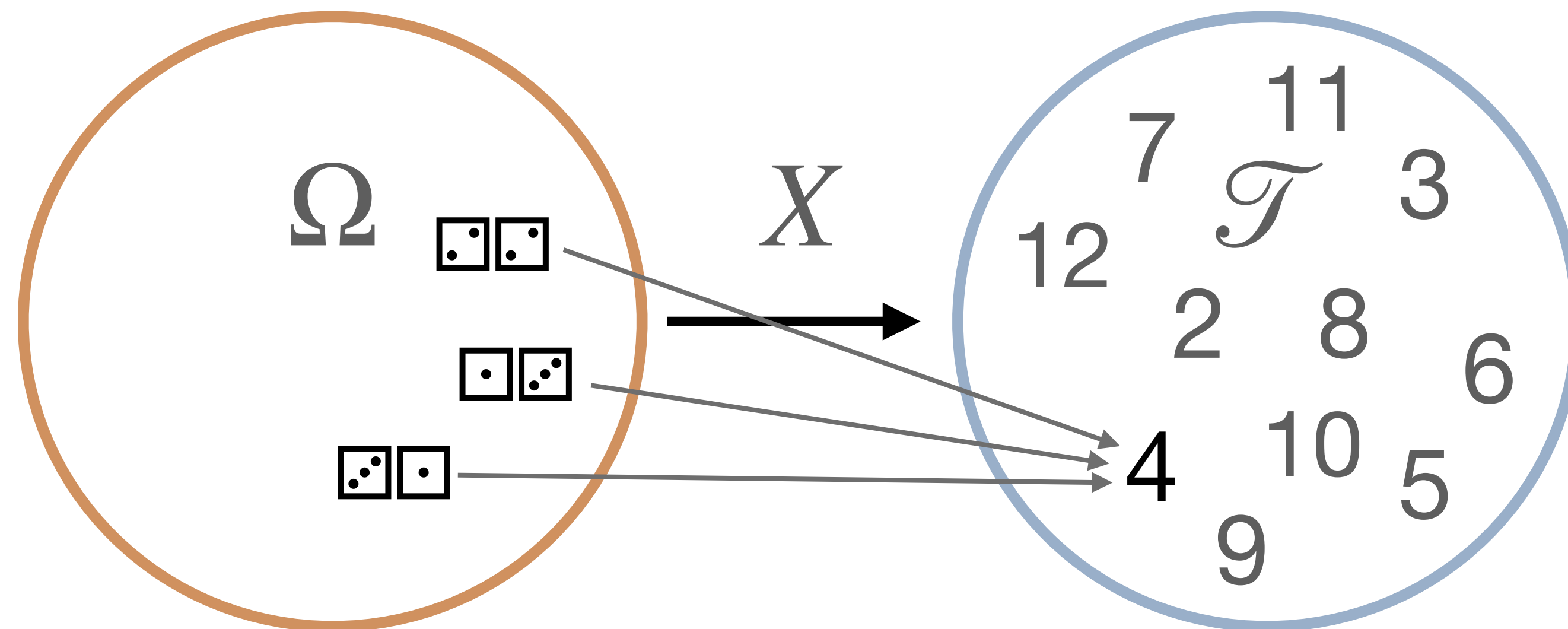
- Consider the set of all possible outcomes of throwing two six-sided dice.
- Then  $\Omega$  can be represented as:

$\{(\square, \square); (\square, \square); (\square, \square); (\square, \square); (\square, \square); (\square, \square); (\square, \square); (\square, \square); (\square, \square); (\square, \square); (\square, \square); (\square, \square);$   
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- One possible random variable we can define is the *sum of the tosses*.
- In that case  $\mathcal{T}$  will be a set of integers from 2 to 12.

# Random Variables

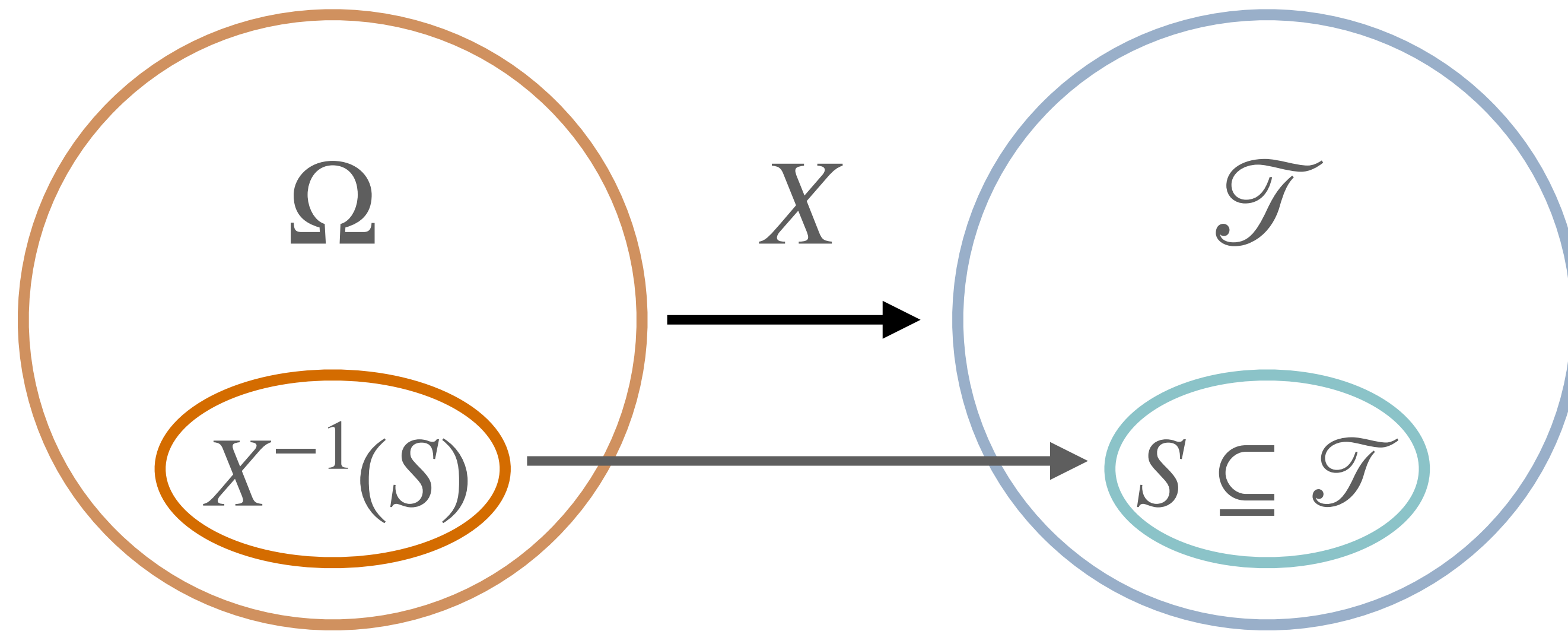
## Example



# Random Variables

## Example

- In general:



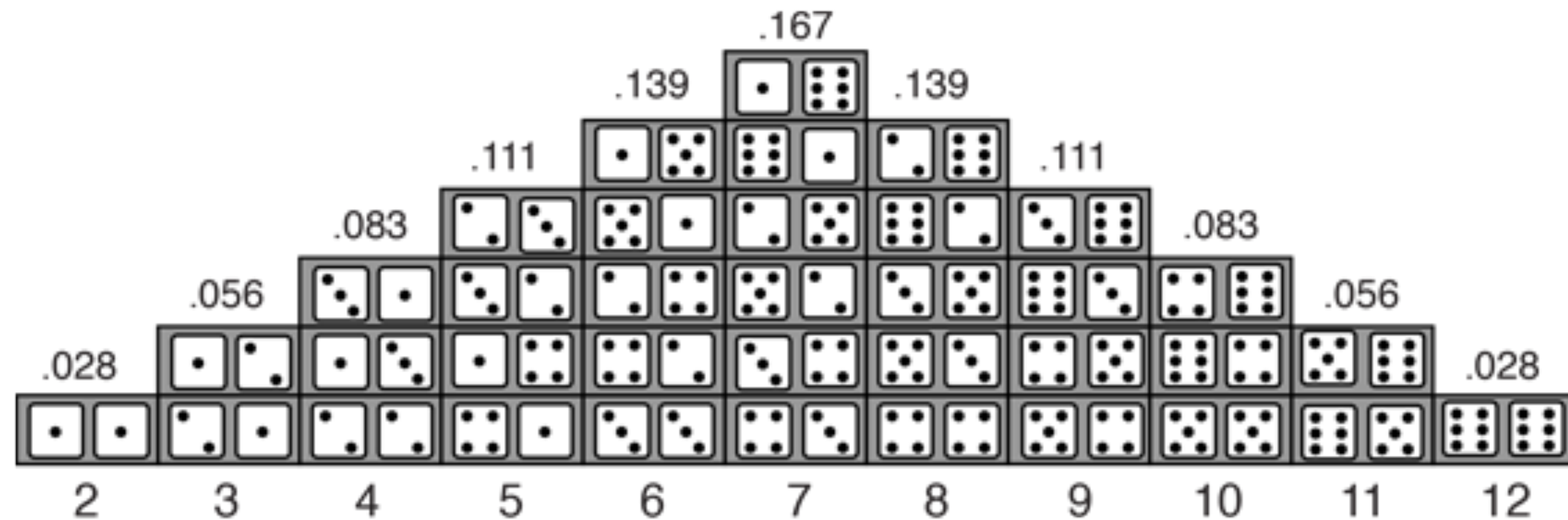
Where  $X^{-1}$  is the subset of  $\Omega$  that if we apply  $X$  would lead to  $S$ .

The probability of subset  $S$  is given by:  $P(S) = P(\omega \in \Omega : X(\omega) \in S)$ .

# Random Variables

## Example

- If we assume that the game of dice is fair, i.e., all outcomes are equally likely, then the probability distribution may look like this:



Total number of microstates: 36

# Random Variables

## One more example

- Experiment: Drawing two coins from the bag (with replacement). The bag contains coins from USA(\$) and UK(£).
- Four possible outcomes:  $\Omega = \{(\$, \$)(\pounds, \pounds), (\$, \pounds), (\pounds, \$)\}$ .
- Assume that there are more \$ coins in the bag so the probability of drawing a £ coin is 0.3.
- Event of interest: *number of times we draw a £.*



# Random Variables

## One more example

- Lets define a random variable  $X$  that maps  $\Omega$  to  $\mathcal{T}$ , which denotes the number of times we draw £ out of the bag.
- From our sample space we can see that we can get 0£, 1£ and 2£s, therefore  $\mathcal{T} = \{0,1,2\}$ .
- Our random variable  $X$  can then be represented like the following:

$$X((\pounds, \pounds)) = 2$$

$$X((\pounds, \$)) = 1$$

$$X((\$, \pounds)) = 1$$

$$X((\$, \$)) = 0$$

# Random Variables

## One more example

- If we assume that draws are independent of each other, the probability can be calculated as follows:

$$P(X = 2) = P((\pounds, \pounds)) = P(\pounds) \times P(\pounds) = 0.3 \times 0.3 = 0.09$$

$$P(X = 1) = P((\pounds, \$)) + P((\$, \pounds)) = P(\pounds) \times P(\$) + P(\$) \times P(\pounds) = 0.3 \times (1 - 0.3) + (1 - 0.3) \times 0.3 = 0.42$$

$$P(X = 0) = ?$$

# Random Variables

## One more example

- If we assume that draws are independent of each other, the probability can be calculated as follows:

$$P(X = 2) = P((\pounds, \pounds)) = P(\pounds) \times P(\pounds) = 0.3 \times 0.3 = 0.09$$

$$P(X = 1) = P((\pounds, \$)) + P((\$, \pounds)) = P(\pounds) \times P(\$) + P(\$) \times P(\pounds) = 0.3 \times (1 - 0.3) + (1 - 0.3) \times 0.3 = 0.42$$

$$P(X = 0) = P((\$, \$)) = P(\$) \times P(\$) = (1 - 0.3) \times (1 - 0.3) = 0.49$$

# Discrete & Continuous Probabilities

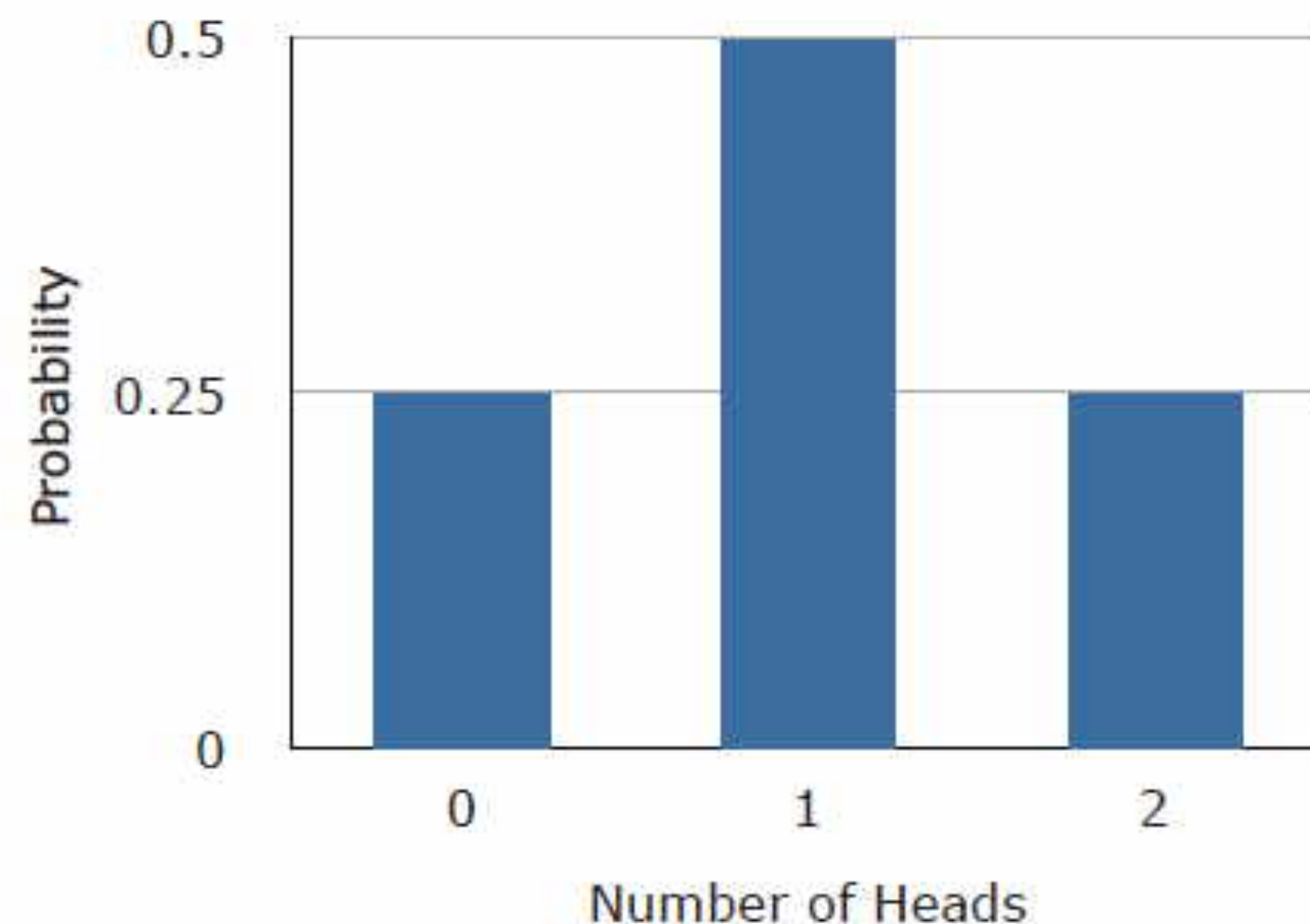
## Introduction

- It is important to understand the difference between target space types.
- Discrete random variables:
  - Variable can take on a *discrete* set of values.
  - Value can be obtained by counting.
- Continuous random variables:
  - Variable can take on a *continuous* set of values.
  - Value can be obtained by measuring.

# Discrete & Continuous Probabilities

## Discrete

- The probability that a random variable  $X$  takes a particular value  $x \in \mathcal{T}$  is denoted as  $P(X = x)$ .
- This expression is also called ***probability mass function***.



$$P(X = 0) = 0.25$$

$$P(X = 1) = 0.5$$

$$P(X = 2) = 0.25$$

# Discrete & Continuous Probabilities

## Discrete

- When the target space is discrete we can imagine the probability distribution of multiple random variables as a multidimensional array of numbers

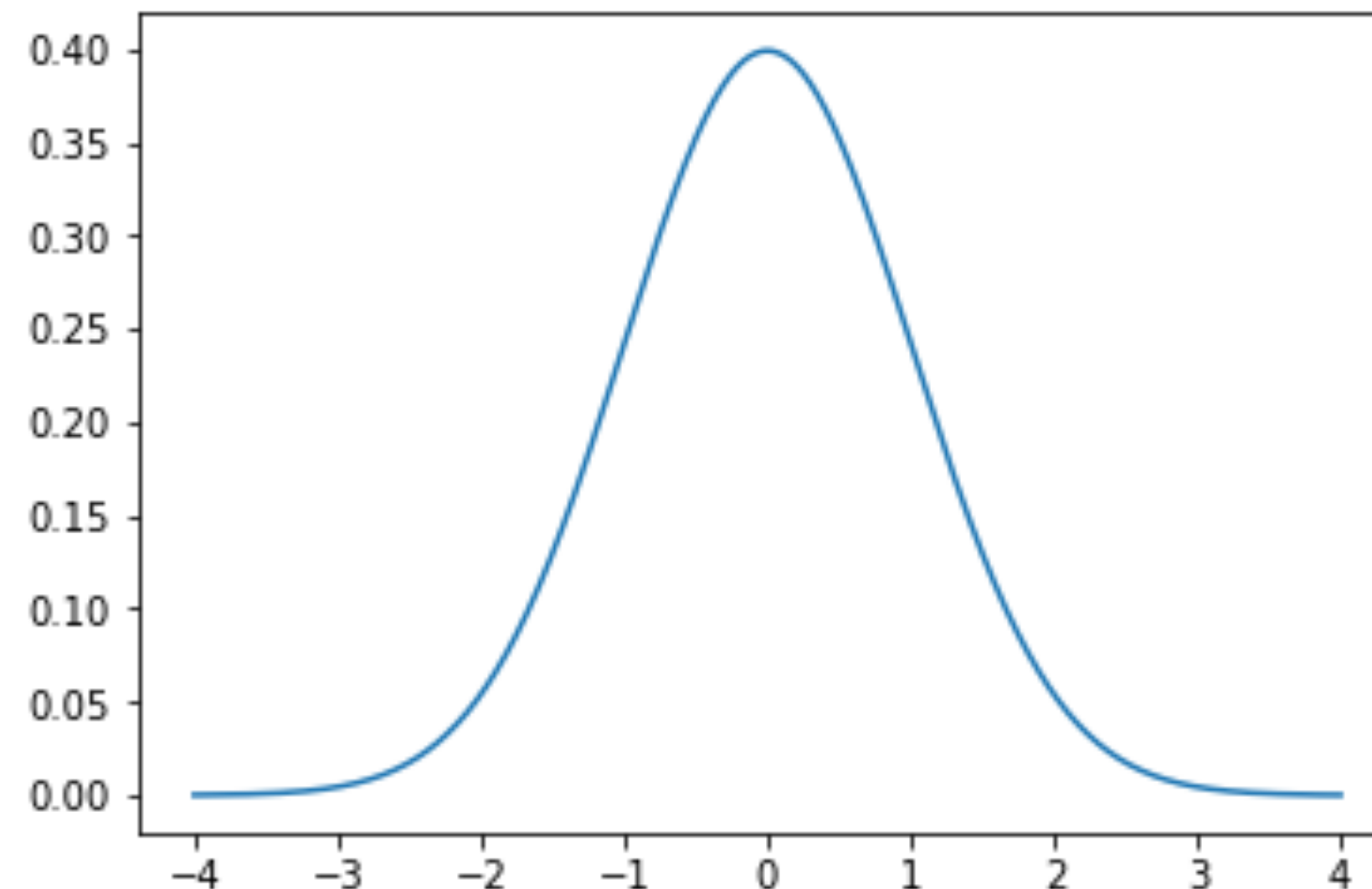
$y_3$	0.1	0.07	0.06	0.03	0.1
$y_2$	0.12	0.09	0.02	0.01	0.05
$y_1$	0.18	0.01	0.11	0.02	0.03
	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$

- ▶ *Joint probability* is defined as  $p(x, y) = P(X = x_i, Y = y_j)$
- ▶ *Marginal probability*  $p(x)$  represents the probability that  $X$  takes the value  $x_i$  irrespective to the value of  $Y$ .
- ▶ *Conditional probability*  $p(y | x)$  will only consider the value of  $Y$  for a particular value of  $X$ .

# Discrete & Continuous Probabilities

## Continuous

- Target spaces are intervals of the real line  $\mathbb{R}$ .
- A ***probability density function*** is a function whose value at any given point in the sample space can be interpreted as providing a *relative likelihood* that the value of the random variable would be close to that sample.



# The Law of Total Probability

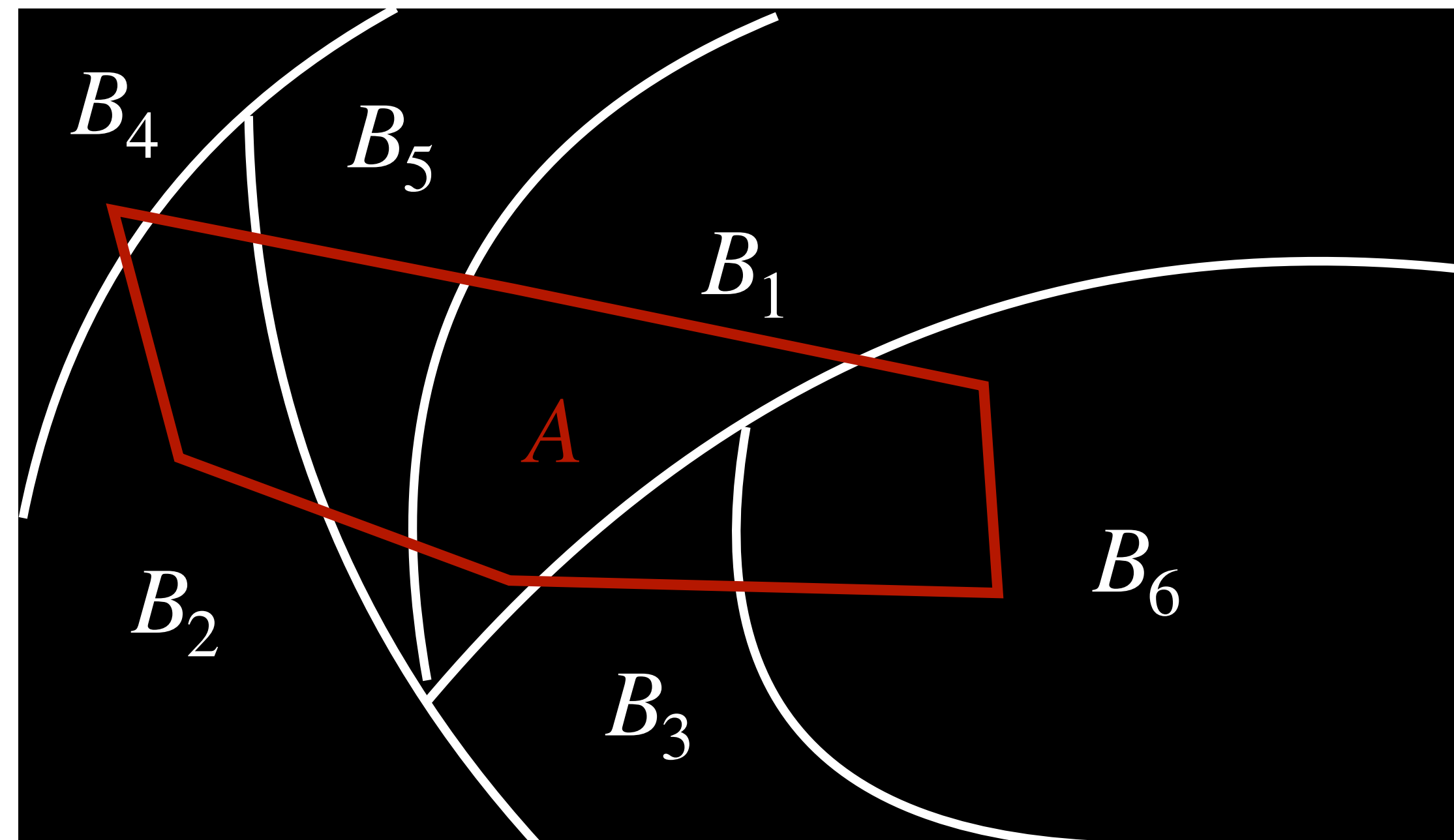
- Suppose  $B_1, \dots, B_n$  are mutually exclusive and collectively exhaustive events in a sample space. We can then sum/integrate over the set of states of variable  $B$  to get a *marginal* distribution of variable  $A$ .

$$P(A) = \sum_i^n P(A | B_i) P(B_i) = \sum_i^n P(A \cap B_i)$$



# The Law of Total Probability

- Mutually exclusive - no overlap.
- Collectively exhaustive - cover the whole space.



# The Law of Total Probability

## Example

- Three robots are making parts at a factory. We know that:
  - Robot 1 makes 60% of the parts.
  - Robot 2 makes 30% of the parts.
  - Robot 2 makes 10% of the parts.
- Some parts that are produced are defective:
  - Of the parts Robot 1 makes, 7% are defective.
  - Of the parts Robot 2 makes, 15% are defective.
  - Of the parts Robot 3 makes, 30% are defective.
- What is the probability of a randomly selected part being defective?

# The Law of Total Probability

## Example

- Three robots are making parts at a factory. We know that:
  - Robot 1 makes 60% of the parts.  $P(R_1) = 0.6$
  - Robot 2 makes 30% of the parts.  $P(R_2) = 0.3$
  - Robot 3 makes 10% of the parts.  $P(R_3) = 0.1$
- Some parts that are produced are defective:
  - Of the parts Robot 1 makes, 7% are defective.  $P(D | R_1) = 0.07$
  - Of the parts Robot 2 makes, 15% are defective.  $P(D | R_2) = 0.15$
  - Of the parts Robot 3 makes, 30% are defective.  $P(D | R_3) = 0.3$
- What is the probability of a randomly selected part being defective?  $P(D) = ?$

# The Law of Total Probability

## Example

$$\begin{aligned}P(D) &= P(D | R_1)P(R_1) + P(D | R_2)P(R_2) + P(D | R_3)P(R_3) \\&= P(D \cap R_1) + P(D \cap R_2) + P(D \cap R_3) \\&= 0.042 + 0.045 + 0.03 \\&= 0.117\end{aligned}$$

# Expectation and Variance

## Definition

- *Expected Value/Mean* gives the weighted average of all possible outcomes of the random variable. *Is not an expected outcome, but a theoretical mean!*

$$\mathbb{E}(X) = \sum x p(x)$$

- *Variance* represents the dispersion, i.e. how far a set of numbers is spread from the mean.

$$Var(X) = \mathbb{E}[(X - \mu)^2] = \sum_x (x - \mu)^2 p(x)$$

- *Standard Deviation* is simply a square root of the variance

$$\sigma_X = \sqrt{Var(X)}$$

# Expected Value

## Exercise

- A computer randomly chooses 4 numbers in range  $[0,10]$ .
- We play a game and try to guess all 4 numbers.
- We pay 3\$ for each game.
- If we win we get 10.000\$.
- What is our expected profit in a long run?

# Expected Value

## Exercise

- Let  $X$  be a random variable representing profit on each play.
- $X \in \{-3, 9997\}$ .
- The probability of making a correct guess...

# Expected Value

## Exercise

- Let  $X$  be a random variable representing profit on each play.
- $X \in \{-3, 9997\}$ .
- The probability of making a correct guess is  $0.1^4 = 0.0001$ .

$X$	$P(X)$	$\mathbb{E}(X)$
$-3$	$0.9999$	?
$9997$	$0.0001$	



# Expected Value

## Exercise

- Let  $X$  be a random variable representing profit on each play.
- $X \in \{-3, 9997\}$ .
- The probability of making a correct guess is  $0.1^4 = 0.0001$ .

$X$	$P(X)$	$\mathbb{E}(X)$
$-3$	$0.9999$	$-2$
$9997$	$0.0001$	

# Expected Value

## One more exercise

- Calculate the expectation for the given random variable:

$x$	0	1	2
$p(x)$	0.16	0.48	0.36

$$\mathbb{E}(X) = \sum_x x p(x) = 0 \times 0.16 + 1 \times 0.48 + 2 \times 0.36 = 1.2$$

# Expected Value

## One more exercise

- Calculate the mean for the given random variable:

$x$	0	1	2
$p(x)$	0.16	0.48	0.36

$$\mathbb{E}(X) = \sum_x x p(x) = 0 \times 0.16 + 1 \times 0.48 + 2 \times 0.36 = 1.2$$

- Now try to calculate the Variance:

$$Var(X) = \sum_x (x - \mu)^2 p(x) = ?$$

# Expected Value

## One more exercise

- Calculate the mean for the given random variable:

$x$	0	1	2
$p(x)$	0.16	0.48	0.36

$$\mathbb{E}(X) = \sum_x x p(x) = 0 \times 0.16 + 1 \times 0.48 + 2 \times 0.36 = 1.2$$

- Now try to calculate the Variance:

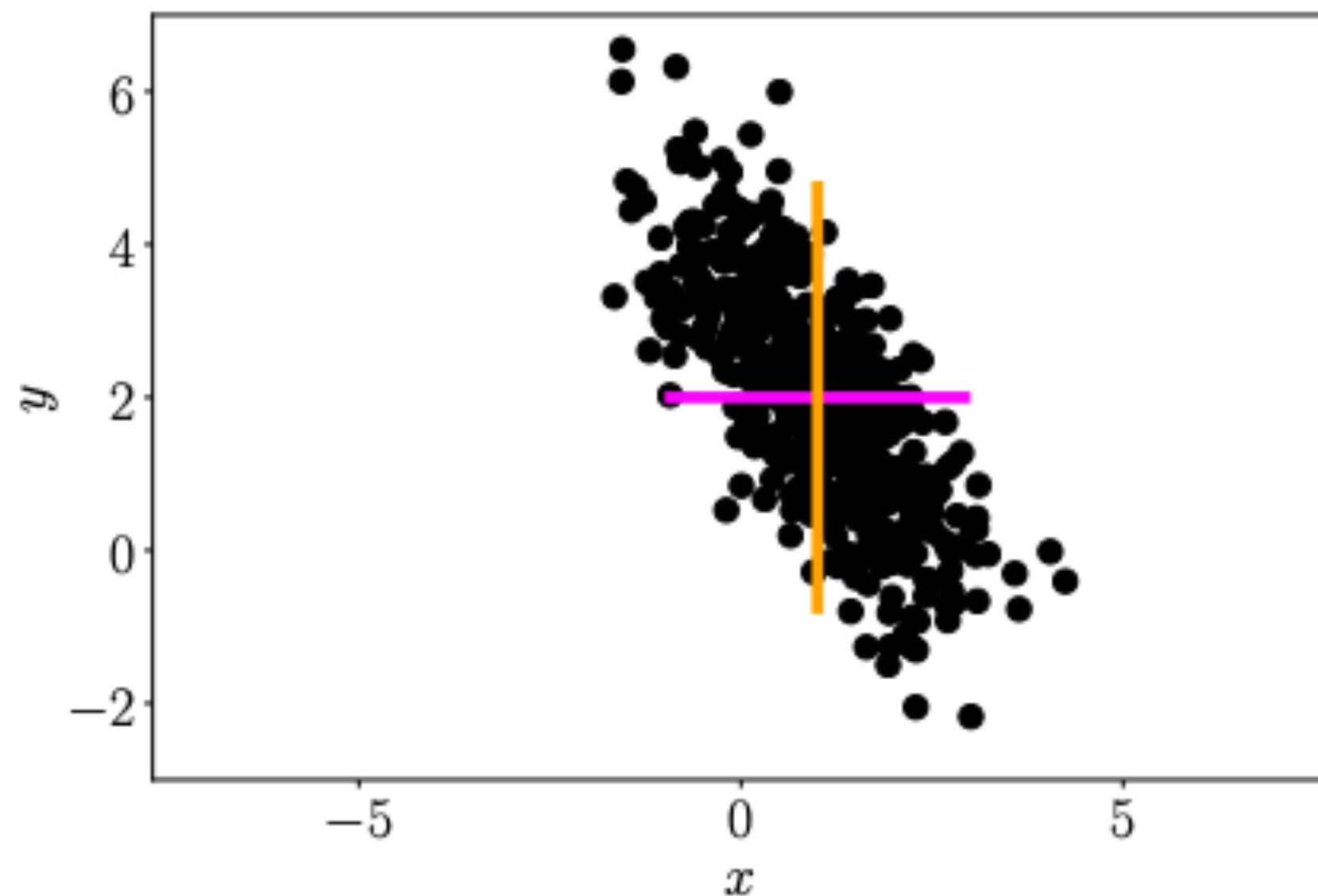
$$\text{Var}(X) = \sum_x (x - \mu)^2 p(x) = 0.48$$

$$\sigma_X = \sqrt{\text{Var}(X)} = \sqrt{0.48}$$

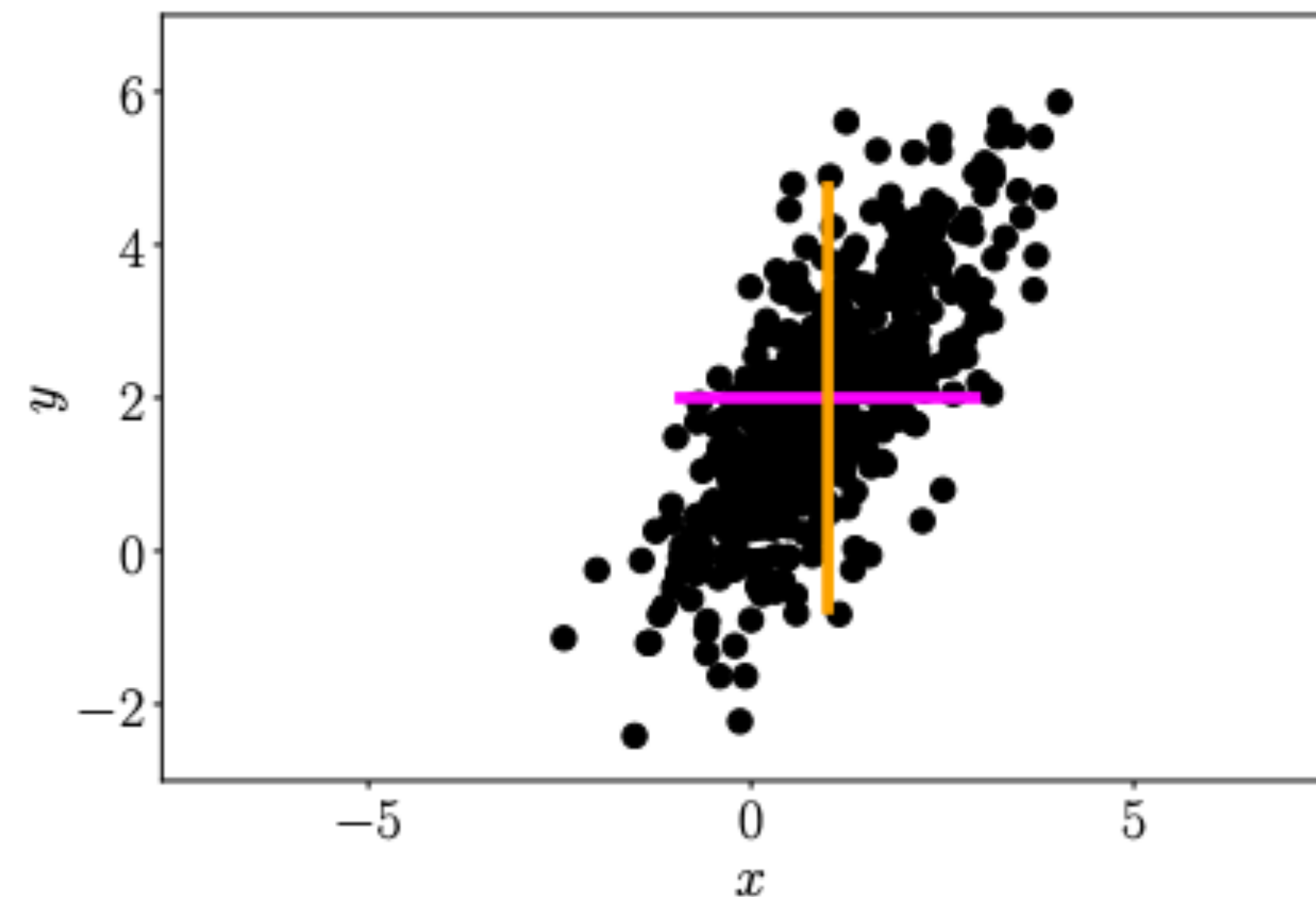
# Covariance

- *Covariance* of two univariate random variables  $X, Y \in \mathbb{R}$  is given by the expected product of their deviations from their respected means.

$$\text{Cov}(X, Y) = \mathbb{E}_{X,Y}[(x - \mathbb{E}_X[x])(y - \mathbb{E}_Y[y])]$$



(a)  $x$  and  $y$  are negatively correlated.



(b)  $x$  and  $y$  are positively correlated.

# Correlation

- *Correlation* is the normalized form of Covariance.

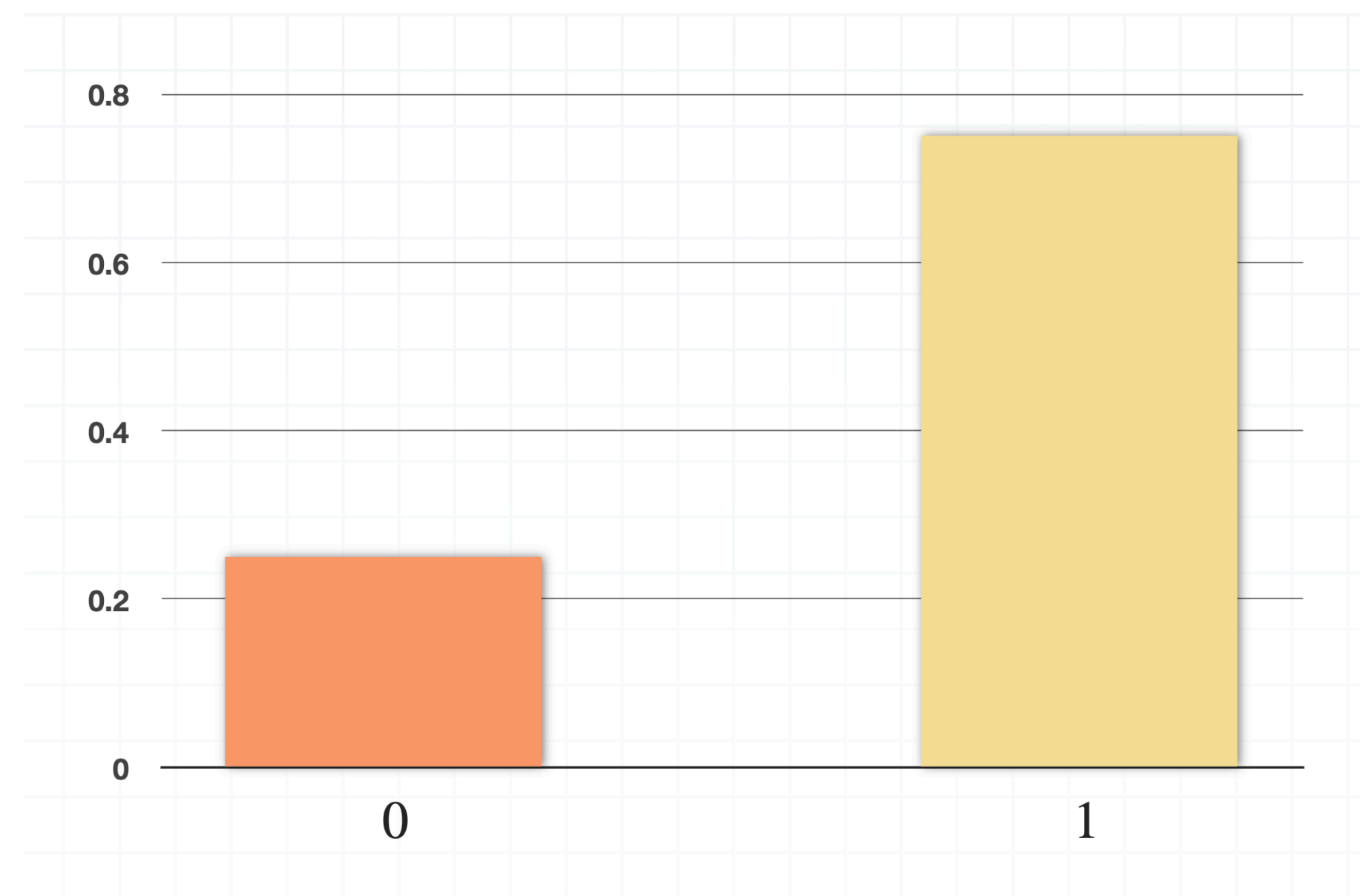
$$\text{Corr}[X, Y] = \frac{\text{Cov}(X, Y)}{\sqrt{\text{Var}(X)\text{Var}(Y)}} \in [-1, 1]$$

- Is useful when we want to compare the covariances between different pairs of random variables.

# Distributions

## Bernoulli distribution

- Models the set of possible outcomes for a *single* experiment.
- $X \in \{0,1\}$
- Parameter  $\rho \in [0,1]$  reflects the probability of getting a 1.
- PMF:  $f(x; p) = \rho^x(1 - \rho)^{1-x}$
- $\mathbb{E}[X] = p$
- Example: tossing a biased coin.



# Distributions

## Binomial distribution

- A generalization of Bernoulli for  $\mathbb{N}$  random variables, i.e.  $X \in \mathbb{N}$ .
- Parameters  $\rho \in [0,1], n \in \mathbb{N} = 0,1,2,3,\dots$
- PMF:  $f(x; p, n) = \binom{n}{k} \rho^x (1 - \rho)^{n-x}$
- $\mathbb{E}[X] = n\rho$



# Distributions

## Binomial distribution

- Let's have a closer look at the PMF:

$$f(x; p, n) = \binom{n}{k} \rho^x (1 - \rho)^{n-x}$$

- Combination

$$\binom{n}{k} = \frac{n!}{k!(n-k)!}$$

Where  $n$  is the total number of possible outcomes,

$k$  is number of items you want to rearrange.

# Useful Links

1. [Intelligent Systems Lab YouTube channel](#)
2. [jbstatistics](#)
3. [3Blue1Brown Probability of Probabilities](#)
4. <https://mml-book.github.io/>
5. [StatQuest!!!](#)